# Steven J. Bellino Traffic Accident Reconstructionist

# California Traffic Specialists

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## California Traffic Specialists

California Traffic Specialists is a company that has integrated a wide variety of complex automotive, human, and biomechanical disciplines into a distinctive professional service. We specialize in the many technical aspects of traffic accident investigation, analysis, and reconstruction. Our highly distinctive professional services include:

## California Traffic Specialists

Traffic Accident Reconstruction **Occupant Kinematics / Biomechanics Vehicle & Occupant Dynamics Human Factors Vehicle Deformation Analysis** Motorcycle Accident Reconstruction **Bicycle / Pedestrian Reconstruction On-Scene Accident Investigation Criminal Vehicular Manslaughter Cases** Fraud / Staged Accident Investigation **Collision Scene Diagramming - CAD Collision Scene Photography / Video Taping** Seat Belt / Child Restraint Analysis Traffic Engineering / Surveying / Design **Speed Surveys / RADAR Operations** Event Data Recorder (EDR) / Crash Data Retrieval (CDR) Analysis **Defensive Driver Training Course Instructions** 

- Our primary objective is to provide our clients with the highest quality of professional support in civil litigations, criminal litigations, and insurance claim investigations.
- Our staff is comprised of court recognized experts (Municipal and Superior) in the various disciplines of traffic accident analysis, investigation, reconstruction, and traffic engineering. Each staff member has given expert testimony in both criminal and civil cases, and is thoroughly familiar with court procedures and decorum. Our staff of accident reconstructionists are nationally accredited and certified by the Accreditation Commission for Traffic Accident Reconstruction (ACTAR). Our staff also consists of a certified Traffic Engineering Technician who has given expert testimony in both criminal and civil cases.

#### STEVEN J. BELLINO TRAFFIC ACCIDENT RECONSTRUCTIONIST

 I am Nationally certified Traffic Accident Reconstructionist and the President of California Traffic Specialists. I served with the Los Angeles Sheriff's Department (LASD) for twenty-seven years and retired at the rank of Sergeant. I served for four years on the Sheriff's Department's specialized Fatal Accident Investigation Team (FAIT). I am nationally accredited and certified as a Traffic Accident Reconstructionist by the Accreditation Commission for Traffic Accident Reconstruction (ACTAR). I am certified by the National Highway Traffic Safety Administration (NHTSA), California Office of Traffic Safety, and U.S. Department of Transportation as a Master Instructor in Occupant Kinematics and Occupant Protection Systems. I am is also certified by the National Safety Council as a Defensive Driver Training Instructor.

My formal education includes a Bachelor of Science degree from California State University Long Beach. I hold a Lifetime State of California Teaching Credential from U.C.L.A. I teach at the community college level. I was an instructor at the Los Angeles County Sheriff's Department's POST advanced traffic accident investigation courses for over twenty years. I currently teach National Safety Council Defensive Driver Training courses in the southern California area.

In 1986, I was selected as a member of the Statewide Traffic Accident Review and **Development Committee for the Department** of Justice, Commission of Peace Officer Standards and Training (POST) which developed and designed each of the four traffic accident investigation courses (Basic, Intermediate, Advanced, Reconstruction) which are presently utilized by all law enforcement agencies and college districts in the State of California.

I have investigated and reconstructed over 8,000 traffic collisions. I have completed over 2,000 hours of specialized training in traffic investigation, reconstruction and biomechanics. I am proficient in all areas of traffic accident reconstruction, biomechanics, occupant kinematics, occupant protection systems, human factors and fraud. The majority of my training was completed at the University of North Florida – Institute of Police Technology and Management, Northwestern University – Traffic Institute, California State Polytechnic University Pomona – TPMI, and Texas A&M University.

I am a court recognized forensic expert in all of the various elements of traffic accident investigation, reconstruction, occupant kinematics, biomechanics and human factors. I have given testimony in over 300 trials in both criminal and civil cases in California Superior Courts and US Federal Courts.

## TRAFFIC ACCIDENT INVESTIGATION & RECONSTRUCTION

Traffic accident reconstruction is the process of gathering and analyzing available data pertaining to a specific traffic collision and determining the events which occurred immediately before, during, and after the collision. The traffic accident reconstruction is only limited by the amount of data, physical evidence and information which is available or provided.

Each traffic accident reconstruction is very unique. The reconstruction may take the form of a simple analysis as in determining if a headlight was incandescent at the time of impact, or may be as complex as recreating the actual collision using exemplar vehicles. The traffic accident reconstruction generally requires the integration of a wide variety of complex automotive and mathematical disciplines to successfully reconstruct the events of the collision. The data used in reconstruction are derived from police reports, vehicle damage examination, accident scene investigation, photographs, examination of physical evidence, medical records, statements from witnesses and involved parties.

Once the formulation is completed, all possible factors pertaining to the collision are considered. The accident reconstruction process yields a collection of critical factors that must be evaluated to reach a valid conclusion. The final results are a set of conclusions and supportive data that will define the events of the collision, injury causation factors, accident avoidance potential, and the cause of the collision.

The traffic accident investigator is also required to determine the causation factors of the collision and determine comparative or associated factors. An analysis of cause may include who had the right-of-way at an intersection, establishing the length of time it would take a vehicle to accelerate from a stop sign to the point of collision, possible collision avoidance maneuvers or calculate a vehicle's speed based on physical evidence.

## THREE PHASES OF ACCIDENT INVESTIGATION & RECONSTRUCTION

Each traffic accident reconstruction is very unique and may require a variety of investigative skills and techniques. Prior to beginning a traffic accident investigation or reconstruction, consideration must be given to the extent and complexity of the available data. An individual who requests a traffic accident investigation and reconstruction should be aware of the available levels to meet their individual needs.

## **VEHICLE INSPECTION**

- Damage and/or deformation analysis.
- Determine the mechanisms of injuries.
- Seatbelt system analysis.
- Headlight examination.
- Tire failure analysis.
- Mechanical inspection.
- Determine if vehicle is supported to obtain a download or image of a vehicle's Event Data Recorder (EDR) or Sensing and Diagnostic Modules (SDM) aka Black Box:
- Photograph and videotape vehicle.

#### **ON-SCENE INVESTIGATION AND COLLECTION OF DATA**

- Obtain Traffic Collision Report, depositions and statements.
- Collision scene examination
- Collision scene measurements.
- Determine the coefficient of friction on the roadway.
- Determine the superelevation of the roadway.
- Determine the slope of the roadway.
- Obtain traffic signal timing charts and scene diagrams.
- Obtain download or image of a vehicle's Event Data Recorder (EDR) or Sensing and Diagnostic Modules (SDM) aka Black Box.

- Environmental factors.
- Vault or fall analysis.
  - Take-off angle.
  - Vertical distance traveled.
  - Horizontal distance traveled.
- Critical speed of the roadway.
- Radius of the roadway.
  - Superelevation, positive or negative.
  - Speed survey via radar.
    - Obtain Medical Records, Autopsy Report, and Coroner's Report.
    - Vision obstructions analysis.
    - Obtain toxicology reports.
    - Photograph and/or videotape scene.
    - Line of sight analysis.

## **RECONSTRUCTION OF DATA**

- Scale diagram of collision scene.
- Scale diagram of vehicle deformation.
- Scale diagram of interior specification.
- Illustration of occupant kinematics.
- Substantiate mechanism of injuries.
- Speed analysis.
- Speed loss from skid marks.
- Speed loss based on deformation.
- Conservation of linear momentum.
- Critical speed of roadway.
- Speed of vehicle from centrifugal tire marks.
- Speed of vehicle at time of vault, fall, or flip.

### Human Factors analysis.

- Evaluation of detection, perception & reaction
- Line of sight analysis
- Components of collision avoidance
- Time and distance analysis.
  - Determine the detection, perception & reaction time
- A plot of each vehicle's or pedestrian's approach to the point of impact in 1/10th of seconds.
- Applicable collision avoidance techniques.
- Recreation of the collision events using exemplar vehicles.
- Results of headlamp examination.
- Vehicle tests: stopping distances, reaction time, maneuverability, acceleration.

- Results of seatbelt analysis.
- Results of tire examination.
- Results of vehicle inspection.
- Diagram and results of occupant kinematic analysis.
- Diagram and results of speed survey.
- Computer generated printouts of all calculations.
- Computer generated graphic displays.
- Photographic displays.
- Videotapes.
- Prepare an animation of the collision event.

## Human Factors

## **Detection, Perception, & Reaction Time**

While performing a task, <u>reaction time</u> in response to the appearance of a particular potential hazard is the time required from the point of initial detection of the hazard in one's field of view, through various stages of evaluation and decision making, to the time that responsive action is taken, which may, depending on circumstances, include either general or attempted precise movement of the hands, feet, or whole body to prevent or control potential impending injury. Such response may also involve the attempted manipulation or engagement of the physical environment, such as the attempted operation of machine controls, the reaching for a handrail, or the positioning of the body or its parts in an attempt to cushion impending impact.

Perception involves the process of not only detecting an object in a general sense, but also *comprehension of its significance*. Perception must occur before reaction can take place. Most objects perceived in one's environment do not receive specific attention. That is, while attention is given to one object, others are not seen with the same clarity. Likewise, an object may be seen but its meaning may not be immediately perceived. Perception delay is the interval between the time that a hazard is reasonably available to be seen and when it is actually seen and fully understood.

If a person, by chance, is looking at the exact place where a simple hazard appears, it will be seen and understood almost instantly, and there is virtually no delay in perception. However, if a person is looking in some other direction, a particular hazard may not be perceived until one's attention either happens to be directed to it, or is somehow drawn to it. This may require several seconds. In many circumstances, individuals may not perceive a hazard before it is actually encountered.

- Four different kinds of reaction time have been recognized in the literature, based on the expectancy and amount of evaluation and decision making required by each.
- Reflex reactions
- Simple reactions
- Complex reactions
- Discriminative reactions

Reflex reactions are instinctive or mostly so and require the shortest time because they involve no thought. An eye blink, the turning of the head away from a strong light, or the withdrawal of a hand from a hot surface are typical reflex actions. When a strong unexpected stimulus is presented to a person, a reflex (hysterical overwhelming or unmanageable fear or emotional excess or sudden / frantic) action may result. Such reflex or startle actions are often wrong and can be disastrous.

Simple reactions (and simple reaction) times) are the most common of human responses to ordinary or routinely encountered situations because the stimulus is reasonably expected and the individual has already decided (and practiced) what is to be done when the stimulus appears. Simple reaction time is often a matter of habit. Such reaction times normally take about a quarter of a second to initiate action. The changing of a green traffic light to yellow or the viewing of a stop sign in a driver's visual field and the typical reactions to them would be examples of simple reaction.

Complex reactions (and accompanying) complex reaction time) generally call for a choice among several possible responses, where the decision related to the most appropriate response has not been made in advance. Even situations involving little ultimate choice can fall into this category. Complex reactions are slower than simple reactions and depend on how complex the stimulus is, how many choices there are for reaction, and how often the individual has been in a similar situation, with response times typically taking from 1.5 to 2.2 seconds or more.

Discriminative reactions (and associated) discriminative reaction time) occur when a person is required to make a choice between two or more actions that are not habitual or practiced. Here, there is a great need to gather information regarding available alternatives, the nature (positive and negative aspects) of each alternative, probabilities regarding the appropriateness (dangers vs. successful hazard avoidance) related to each alternative, as well as the possible moral issues of the alternatives. This is the slowest of all the reactions and may require as much a five seconds to a minute if the situation is complicated and the urgency slight. When the situation is urgent, there is a high probability that the response will be inappropriate or no response will be initiated before it is too late to respond at all.

#### **TIME & DISTANCE ANALYSIS**

#### **Perception/Reaction & Braking Times and Distances**

SPEED (mph)	FPS	Perception/ Reaction <u>TIME</u>	REACTION DISTANCE	BRAKING DISTANCE	BRAKING <u>TIME</u>	TOTAL STOPPING DISTANCE	TOTAL STOPPING <u>TIME</u>
35	51.34	1.50	77.01	56.80	2.20	133.81	3.70
40	58.68	1.50	88.02	74.20	2.50	162.40	4.00
45	66.00	1.50	99.00	93.90	2.80	192.90	4.30

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#### **TIME & DISTANCE ANALYSIS**

#### **Perception/Reaction & Braking Times and Distances**

SPEED (mph)	FPS	Perception/ Reaction <u>TIME</u>	REACTION DISTANCE	BRAKING DISTANCE	BRAKING <u>TIME</u>	TOTAL STOPPING DISTANCE	TOTAL STOPPING <u>TIME</u>
35	51.34	2.0	102.68	56.80	2.20	159.48	4.20
40	58.68	2.0	117.36	74.20	2.50	191.56	4.50
45	66.00	2.0	132.00	93.90	2.80	225.90	4.80

# HUMAN FACTORS IN TRAFFIC CRASHES

Jeffrey W. Muttart

Volume 1: Determining the Time Available to the Driver

Walking Speeds, Vehicle Acceleration, Sight Lines & Nighttime Analysis



# **Eccentricity**

- A mathematical constant that for a given conic section is the ratio of the distances from any point of the conic section to a focus and the corresponding directrix.
- Conic Section: a plane curve, line, pair of intersecting lines, or point that is the intersection of or bounds the intersection of a plane and a cone with two nappes which is one of the two sheets that lie on opposite sides of the vertex and together make up a cone.
- Directrix: a fixed curve with which a generatrix (a point, line, or surface whose motion generates a line, surface, or solid) maintains a given relationship in generating a geometric figure; : a straight line the distance to which from any point of a conic section is in fixed ratio to the distance from the same point to a focus.

PATH INTRUSION	×	2	S bELLINO	CSS, LLC		DESDONCE TO DATH INTRUSION	1
5. Hazard & Appro Res	sponse Unknown ***	*DEFAULT***	Peo	destrian Isabel Pablo		ALS CROLIGIAN MACSICA	
4. Road/HI Fidelity Sim	1	***DEFAULT***	Check if t	using Mobile Phone		Officer Boulerice	
1. Response to one ob	ject	Offset @ start of Intra	s 7.4	1. Driving	$\mathbf{\nabla}$	Primary Driver	- 1947) - 1947)
*CALCULATE ECCENT	RICITY*	Dist to Intrude	r 127.8	0. SV Not Turning		Initial Speed 35.0 mph	
1. Straight Road		Eccentricit	y 3.3	1. Day		Braking Respon	
3 Full Response (250	ms veh delav)	•	1. Subj did not	discern other unit stop	•	3.0	
Check if hoverir	ng brake					Avg. Deceleration factor 0.8 gs	
	ig brand				Second second	S bELLINO © CSS,	LLC
and the second							
Braking Adj + (413 x T	r) + 30E + 224Lt + 7	16O - 496Tp - 164M + 261T	n + 350(D - 1) + 7	7 eq.1		Response Distance = ~ 1.7 x 35 x 1.467	eq.3
Braking Adj + (413 x T 0 + (413 x 3) -	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 +	160 - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26	īn + 350(D - 1) + 7 1x0 + 350 x (1 - 1	7 eq.1 ) + 7 eq.2		Response Distance = ~ 1.7 x 35 x 1.467 Distance to Stop = (35 x 1.467)^2 / (2 x 32.2 x 0.8)	eq.3 eq.4
Braking Adj + (413 x T 0 + (413 x 3) -	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 +	160 - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26	n + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile	7 eq.1 ) + 7 eq.2 response		Response Distance = $\sim$ 1.7 x 35 x 1.467 Distance to Stop = (35 x 1.467) $^2$ / (2 x 32.2 x 0.8) Total Stopping Distance = 88 feet + 51 feet	eq.3 eq.4 eq.5
Braking Adj + (413 x T 0 + (413 x 3) - AVERAGE PRT	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 + <b>1.7 sec</b>	160 - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26	in + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile 2.3 sec	7 eq.1 ) + 7 eq.2 response Individuals		Response Distance = $\sim$ 1.7 x 35 x 1.467 Distance to Stop = (35 x 1.467) <sup>2</sup> / (2 x 32.2 x 0.8) Total Stopping Distance = 88 feet + 51 feet Time to Brake = SQRT(2d / g x f) = 2 sec	eq.3 eq.4 eq.5 eq.6
Braking Adj + (413 x T 0 + (413 x 3) - AVERAGE PRT Equation	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 + 1.7 sec 1.6 sec	160 - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26	in + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile 2.3 sec	7 eq.1 ) + 7 eq.2 response Individuals		Response Distance = $\sim 1.7 \times 35 \times 1.467$ Distance to Stop = $(35 \times 1.467)^2 / (2 \times 32.2 \times 0.8)$ Total Stopping Distance = 88 feet + 51 feet Time to Brake = SQRT(2d / g x f) = 2 sec TOT. STOPPING DIST. <u>139 feet</u>	eq.3 eq.4 eq.5 eq.6 eq.5
Braking Adj + (413 x T 0 + (413 x 3) - <u>AVERAGE PRT</u> Equation	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 + 1.7 sec 1.6 sec	160 - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26 Min Avg	in + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile 2.3 sec Max Avg	7 eq.1 ) + 7 eq.2 response Individuals		Response Distance = $\sim 1.7 \times 35 \times 1.467$ Distance to Stop = $(35 \times 1.467)^2 / (2 \times 32.2 \times 0.8)$ Total Stopping Distance = 88 feet + 51 feetTime to Brake = SQRT(2d / g x f) = 2 secTOT. STOPPING DIST. 139 feetAVG. Response Dist. 88 feet	eq.3 eq.4 eq.5 eq.6 eq.5 eq.3
Braking Adj + (413 x T 0 + (413 x 3) - <u>AVERAGE PRT</u> Equation A2B studies	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 + 1.7 sec 1.6 sec 1.8 Sec	16O - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26 Min Avg 1.4 Sec	in + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile 2.3 sec Max Avg 2.1 Sec	7 eq.1 ) + 7 eq.2 response Individuals Scenarios		Response Distance = $\sim 1.7 \times 35 \times 1.467$ Distance to Stop = $(35 \times 1.467)^2 / (2 \times 32.2 \times 0.8)$ Total Stopping Distance = 88 feet + 51 feetTime to Brake = SQRT(2d / g x f) = 2 secTOT. STOPPING DIST. 139 feetAVG. Response Dist. 88 feet85th percentile response Dist. 119 feet	eq.3 eq.4 eq.5 eq.6 eq.5 eq.3
Braking Adj + (413 x T 0 + (413 x 3) - AVERAGE PRT Equation A2B studies Resp to Vehicle	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 + 1.7 sec 1.6 sec 1.8 Sec 1.8 Sec	16O - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26 Min Avg 1.4 Sec 1.5 Sec	n + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile 2.3 sec Max Avg 2.1 Sec 2.0 Sec	7 eq.1 ) + 7 eq.2 response Individuals Scenarios		Response Distance = $~1.7 \times 35 \times 1.467$ Distance to Stop = $(35 \times 1.467)^2 / (2 \times 32.2 \times 0.8)$ Total Stopping Distance = 88 feet + 51 feetTime to Brake = SQRT(2d / g x f) = 2 secTOT. STOPPING DIST. 139 feetAVG. Response Dist.88 feet85th percentile response Dist.119 feetStopping Dist.51 feet	eq.3 eq.4 eq.5 eq.6 eq.5 eq.3
Braking Adj + (413 x T 0 + (413 x 3) - AVERAGE PRT Equation A2B studies Resp to Vehicle Resp to Ped.	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 + 1.7 sec 1.6 sec 1.8 Sec 1.8 Sec 1.8 Sec 1.8 Sec	16O - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26 Min Avg 1.4 Sec 1.5 Sec 1.5 Sec 1.5 Sec	n + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile 2.3 sec Max Avg 2.1 Sec 2.0 Sec 2.1 Sec	7 eq.1 ) + 7 eq.2 response Individuals Scenarios		Response Distance = $~1.7 \times 35 \times 1.467$ Distance to Stop = $(35 \times 1.467)^2 / (2 \times 32.2 \times 0.8)$ Total Stopping Distance = 88 feet + 51 feetTime to Brake = SQRT(2d / g x f) = 2 secTOT. STOPPING DIST. 139 feetAVG. Response Dist.88 feet85th percentile response Dist.119 feetStopping Dist.51 feet	eq.3 eq.4 eq.5 eq.6 eq.5 eq.3
Braking Adj + (413 x T 0 + (413 x 3) - AVERAGE PRT Equation A2B studies Resp to Vehicle Resp to Vehicle Resp to Ped. Resp to Object	r) + 30E + 224Lt + 7 + 30x3.3 + 224x1 + 1.7 sec 1.6 sec 1.8 Sec 1.8 Sec 1.8 Sec 1.8 Sec 1.8 Sec	160 - 496Tp - 164M + 261T 716x1 - 496x1 - 164x1 + 26 Min Avg 1.4 Sec 1.5 Sec 1.5 Sec 1.4 Sec	in + 350(D - 1) + 7 1x0 + 350 x (1 - 1 85th percentile 2.3 sec Max Avg 2.1 Sec 2.0 Sec 2.1 Sec 2.0 Sec 2.0 Sec	7 eq.1 ) + 7 eq.2 response Individuals Scenarios		Response Distance = $\sim 1.7 \times 35 \times 1.467$ Distance to Stop = $(35 \times 1.467)^2 / (2 \times 32.2 \times 0.8)$ Total Stopping Distance = 88 feet + 51 feetTime to Brake = SQRT(2d / g x f) = 2 secTOT. STOPPING DIST. 139 feetAVG. Response Dist.88 feet85th percentile response Dist.119 feetStopping Dist.51 feet	eq.3 eq.4 eq.5 eq.6 eq.5 eq.3 eq.4

PATH INTRUSION		$\mathbf{\nabla}$	S bELLINO	OCSS, LLC			DESDANCE TA DATE INTRUCIA	61
5. Hazard & Appro Re	esponse Unknown *	**DEFAULT***	Pe	destrian Isabel	Pablo		ALDFUNDL IV FAITHINTKUDIU	N
4. Road/HI Fidelity Si	m	***DEFAULT***	Check if	using Mobile Pho	ne		Officer Boulerice	
1. Response to one o	bject	Offset @ start of Intr	s 7.4	1. Driving		V	Primary Driver	
*CALCULATE ECCENT	TRICITY*	▼ Dist to Intrude	r 127.8	0. SV Not Tu	rning	V	Initial Speed 40.0 mph	
1. Straight Road		Eccentricit	y 3.3	1. Day		•	Braking Respon	
3 Full Response (25)	0 ms veh delav)		1. Subj did not	discern other uni	it stop	•	3.0	
	ing brake	************				V	Avg. Deceleration factor 0.8 gs	
							S bELLINO © CSS,	LLC
Braking Adj + (413 x	Tr) + 30E + 224Lt +	716O - 496Tp - 164M + 2611	în + 350(D - 1) + 1	7	eq.1		Response Distance = ~ 1.7 x 40 x 1.467	eq.3
0 + (413 x 3)	+ 30x3.3 + 224x1	+ 716x1 - 496x1 - 164x1 + 26	1x0 + 350 x (1 - 1	) + 7	eq.2		Distance to Stop = (40 x 1.467)^2 / (2 x 32.2 x 0.8)	eq.4
			85th percentile	response			Total Stopping Distance = 100 feet + 67 feet	eq.5
AVERAGE PRT	1.7 sec		2.3 sec	Individuals			Time to Brake = SQRT(2d / g x f) = 2.3 sec	eq.6
Equation	1.6 sec						TOT. STOPPING DIST. 167 feet	eq.5
		Min Avg	Max Avg				AVG. Response Dist. 100 feet	eq.3
A2B studies	1.8 Sec	1.4 Sec	2.1 Sec	Scenarios			85th percentile response Dist. 136 feet	
Resp to Vehicle	1.8 Sec	1.5 Sec	2.0 Sec				Stopping Dist. 67 feet	eq.4
Resp to Ped.	1.8 Sec	1.5 Sec	2.1 Sec					
Resp to Object	1.8 Sec	1.4 Sec	2.0 Sec				85th percentile respo	
							85th %ile STOPPING DIST. 203 feet	

Officer Boulerice		
Lateral Acceleration [fy] (gs)	0.20	
Lateral distance to avoid feet		σ
Expected Deceleration [fx] (gs)	0.80	0.08
nitial speed mph	35.00	5.00
Actual Deceleration [fx] (gs)	0.85	
Pre-Impact Maneuver Dist feet	58.60	
Final Speed necessary to avoid mph	0.00	
Time available (seconds)	1.87	
Perception-response time (seconds)	1.70	0.59
- Time remaining (Available - PRT) (sec.)	0.17	
Additional Time necessary? (sec)	0.79	
CTEED		
<u>STEER</u> This driver could steen 0 feet right or left before i	mpact	
Time to stoer = 0 seconds	inpaci.	
Time to steer = 0 seconds		
$1 \text{ steer} = \text{SQR1}(2 \times 7 (32.2 \times 0.2))$		1 40/
STOP		1.4%
Driver was approx. 95.8 feet from impact at onse	et and could NOT stop in t	nat distance
Time to stop = 2 seconds		
Istop = (35 x 1.467) / (32.2 x 0.8)	- 120 2 1/ 41 1 feat	
Total stopping distance = Resp. Dist. + Stop Dist. +	= 138.3 +/- 41.1 teet	
Avg. Resp. Dist. = $1.697 \times 35 \times 1.467 = 87.1$ feet	0.0) 54.25	
Avg. Stopping Dist. = (35 x 1.467)^2 / (2 x 32.23	x 0.8) = 51.2 feet	
Total 851H% Stopping Dist. = 85th% Kesp. Dist. +	85th% Stop Dist. = 1/4.5 t	eet
85th% Resp. Dist. = 2.29 X 35 X 1.467 = 117.6 fe	et	
85th% Stopping Dist. = (35 x 1.467)^27 (2 x 32.	$2 \times (0.8 - 0.08)) = 56.9$ feet	
<u>slow</u>		
Slowest possible speed in time remaining = 32 mp	bh	
d = 35 x 1.467 x 0.168 - 0.5 x 32.2 x 0.8 x 0.168'	^2 = 8.3 ft	
Sf = SQRT((35 x 1.467)^2 - 2 x 32.2 x 0.8 x 8.3) /	1.467	
Slowest possible speed with the additional time =	: 18.2 mph	
d = 35 x 1.467 x 0.958 - 0.5 x 32.2 x 0.8 x 0.958	^2 = 37.4 ft	% who Could Slow
Avg. Total Slowing Dist. = 124.5 feet +/- 30.5 fe	et	0.6%
This driver could not slow to 0 mph in time remain	ning.	
This driver could not slow enough to travel -152.0	6 feet in 0.958 sec.	
Time to clow from 35 mph to 0 mph = 2 seconds		

S bELLINO © CSS, LLC

Tslow = (35 - 0) x 1.467 / (32.2 x 0.8)

#### **AVOIDANCE** WITH FINITE DIFFERENCE ANALYSIS



□ fx = 0.8 ■ Driver's Range ■ fy=0.2

Officer Boulerice		
Lateral Acceleration [fy] (gs)	0.20	
Lateral distance to avoid feet		σ
Expected Deceleration [fx] (gs)	0.80	0.08
Initial speed mph	40.00	5.00
Actual Deceleration [fx] (gs)	0.85	
Pre-Impact Maneuver Dist feet	58.60	
Final Speed necessary to avoid mph	0.00	
Time available (seconds)	1.87	
Perception-response time (seconds)	1.70	0.59
Time remaining (Available - PRT) (sec.)	0.17	
Additional Time necessary? (sec)	0.79	
<u>STEER</u> This driver could steer 0 feet right or left before ir	npact.	
Time to steer = 0 seconds		
Tsteer = SQRT(2 x / (32.2 x 0.2)		
<u>STOP</u>		0.5%
Driver was approx. 109.4 feet from impact at ons	et and could NOT stop in t	hat distance
Time to stop = 2.3 seconds		
Tstop = (40 x 1.467) / (32.2 x 0.8)		
Total stopping distance = Resp. Dist. + Stop Dist. =	= 166.4 +/- 45.9 feet	
Avg. Resp. Dist. = 1.697 x 40 x 1.467 = 99.6 feet		
Avg. Stopping Dist. = (40 x 1.467)^2 / (2 x 32.2 x	(0.8) = 66.8 feet	
Total 85TH% Stopping Dist. = 85th% Resp. Dist. +	85th% Stop Dist. = 208.7 fe	et
85th% Resp. Dist. = 2.29 x 40 x 1.467 = 134.4 fe	et	
85th% Stopping Dist. = (40 x 1.467)^2 / (2 x 32.2	2 x (0.8 - 0.08)) = 74.3 feet	
<u>SLOW</u>		
Slowest possible speed in time remaining = 37 mp	h	
d = 40 x 1.467 x 0.168 - 0.5 x 32.2 x 0.8 x 0.168^	2 = 9.5 ft	
Sf = SQRT((40 x 1.467)^2 - 2 x 32.2 x 0.8 x 9.5) /	1.467	
Slowest possible speed with the additional time =	23.2 mph	
d = 40 x 1.467 x 0.958 - 0.5 x 32.2 x 0.8 x 0.958^	2 = 44.4 ft	% who Could Slow
Avg. Total Slowing Dist. = 144 feet +/- 34.9 feet		0.3%
This driver could not slow to 0 mph in time remain	ning.	
This driver could not slow enough to travel -182.8	feet in 0.958 sec.	
Time to slow from 40 mph to 0 mph = 2.3 seconds		

Tslow = (40 - 0) x 1.467 / (32.2 x 0.8)

#### AVOIDANCE

WITH FINITE DIFFERENCE ANALYSIS



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